

§ 1.7 Linear Independence

- Given a set of vectors $\{v_1, v_2, \dots, v_\ell\}$ of \mathbb{R}^n ,
- We say $\{v_1, \dots, v_\ell\}$ is linearly independent if the vector equation

$$x_1 v_1 + x_2 v_2 + \dots + x_\ell v_\ell = 0$$

has only the trivial solution ($x = 0$).

- We say $\{v_1, \dots, v_\ell\}$ is linearly dependent if there is a nontrivial solution to the equation above. I.e. there are real numbers c_1, \dots, c_ℓ not all zero such that

$$c_1 v_1 + \dots + c_\ell v_\ell = 0$$

Such an equation is called an equation (or relation) of linear dependence.

Remark

- Let v be a vector. The set $\{v\}$ is linearly independent if and only if $v \neq 0$.
- A set of two vectors $\{v_1, v_2\}$ is linearly independent if and only if neither of the two vectors is a multiple of the other.

Using the terminology from last time:

Theorem

$\{v_1, \dots, v_k\}$ is linearly independent if and only if the matrix equation $Ax=0$ has only the trivial solution where $A = [v_1 | v_2 | \dots | v_k]$.

Example

Determine if v_1, v_2, v_3 are linearly independent where

$$v_1 = \begin{bmatrix} 3 \\ 4 \\ 6 \end{bmatrix}, \quad v_2 = \begin{bmatrix} -4 \\ 4 \\ 8 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 6 \\ 8 \\ 12 \end{bmatrix}$$

Solve $Ax=0$

$$\left[\begin{array}{ccc|c} 3 & -4 & 6 & 0 \\ 4 & 4 & 8 & 0 \\ 6 & 8 & 12 & 0 \end{array} \right] \xrightarrow{\frac{1}{3}R_1} \left[\begin{array}{ccc|c} 1 & -\frac{4}{3} & 2 & 0 \\ 4 & 4 & 8 & 0 \\ 6 & 8 & 12 & 0 \end{array} \right] \xrightarrow{\begin{array}{l} -4R_1 + R_2 \rightarrow R_2 \\ -6R_1 + R_3 \rightarrow R_3 \end{array}}$$

$$\left[\begin{array}{ccc|c} 1 & -\frac{4}{3} & 2 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 16 & 0 & 0 \end{array} \right] \xrightarrow{\frac{3}{20}R_2} \left[\begin{array}{ccc|c} 1 & -\frac{4}{3} & 2 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 16 & 0 & 0 \end{array} \right] \xrightarrow{\begin{array}{l} \frac{1}{3}R_2 + R_1 \rightarrow R_1 \\ -16R_2 + R_3 \rightarrow R_3 \end{array}}$$

x_3 free so infinitely many nontrivial solutions!

$$\begin{cases} x_1 = -2x_3 \\ x_2 = 0 \\ x_3 = \text{free} \end{cases}$$

$$\text{solution set} = \text{span} \left\{ \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \right\}$$

No! $\{v_1, v_2, v_3\}$ is not linearly independent.

$$-2v_1 + 0v_2 + v_3 = 0$$

Theorem

The set $\{v_1, \dots, v_l\}$ where $l \geq 2$ is linearly dependent if and only if at least one of the vectors v_1, \dots, v_l is a linear combination of the others

Proof

By definition of linear dependence

$$c_1 v_1 + c_2 v_2 + \dots + c_l v_l = 0$$

where at least one of the c_1, \dots, c_l is nonzero.

Say $c_i \neq 0$ for some $1 \leq i \leq l$. Then

$$c_1 v_1 + \dots + c_{i-1} v_{i-1} + c_{i+1} v_{i+1} + \dots + c_l v_l = -c_i v_i$$

so

$$-\frac{c_1}{c_i} v_1 + \dots + \left(\frac{c_{i-1}}{-c_i}\right) v_{i-1} + \left(\frac{c_{i+1}}{-c_i}\right) v_{i+1} + \dots + \left(\frac{c_l}{-c_i}\right) v_l = v_i$$

so v_i is a linear combination of $\{v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_l\}$

Warning!

This theorem does not say ~~at~~ every vector is a linear combination of ~~them~~ others, but that at least one is.

For example $\{v_1, v_2, v_3\}$ is linearly dependent

where

$$v_1 = \begin{bmatrix} 3 \\ 4 \\ 6 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} -4 \\ 4 \\ 8 \end{bmatrix}$$

$$v_3 = \begin{bmatrix} 6 \\ 8 \\ 12 \end{bmatrix}$$

but v_2 is not a linear combination of v_1 and v_3 .
check this!

As a follow-up to the previous theorem, we have the following result. (Useful for written Hw §1.7 Pg 65 #82)

Theorem

Suppose $\{v_1, \dots, v_k\}$ is a linearly independent set. Then w is in $\text{span}\{v_1, \dots, v_k\}$ if and only if $\{v_1, \dots, v_k, w\}$ is linearly dependent.

Proof

\Rightarrow Suppose w in $\text{span}\{v_1, \dots, v_k\}$. Then $c_1 v_1 + \dots + c_k v_k = w$ for some c_1, \dots, c_k in \mathbb{R} (not all zero)

$$\text{Then } c_1 v_1 + \dots + c_k v_k - 1 \cdot w = 0$$

so $\{v_1, \dots, v_k, w\}$ is linearly dependent since not all of c_1, \dots, c_k are zero.

\Leftarrow Suppose $\{v_1, \dots, v_k, w\}$ is linearly dependent. Then $c_1 v_1 + \dots + c_k v_k + d w = 0$ for c_1, \dots, c_k, d in \mathbb{R} not all zero

Now if $d=0$, then $c_1 = \dots = c_k = 0$ too since $\{v_1, \dots, v_k\}$ is linearly independent, but at least one of c_1, \dots, c_k, d is nonzero so this can't happen. Thus $d \neq 0$ and so

$$-d w = c_1 v_1 + \dots + c_k v_k$$

$$w = \left(-\frac{c_1}{d}\right)v_1 + \dots + \left(-\frac{c_k}{d}\right)v_k \quad \text{since } d \neq 0$$

so indeed w is in $\text{span}\{v_1, \dots, v_k\}$.

□

Theorem

If a ~~set~~ set contains more vectors than there are entries in each vector, then the set is linearly dependent. In other words if $\{v_1, \dots, v_l\}$ is a set of vectors in \mathbb{R}^n , then $\{v_1, \dots, v_l\}$ is linearly dependent if $l > n$.

Proof

$\{v_1, \dots, v_l\}$ is linearly independent if $Ax = 0$ has only the trivial solution where $A = [v_1 \dots v_l]$. However this is impossible since $l > n$ as there are more variables than columns and so there must be a free variable (since at most $n < l$ pivot columns).

Warning!

This theorem says nothing about $\{v_1, \dots, v_l\}$ in \mathbb{R}^n if $l \leq n$.

For example, in \mathbb{R}^3

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \right\}$$

is linearly independent

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ -2 \\ -3 \end{bmatrix} \right\}$$

is linearly dependent